Inverted Indexing, MT, MapReduce



4/4/2016 CSE 5/624 PSLC

Game plan for today:

Quick overview of inverted indexing

Inverted indexing & Map-Reduce

Quick MT overview

Map-Reduce & MT Model Estimation

Information Retrieval 101:

We have a set of documents...

... and we want to be able to search them by the terms that they contain.

. . .



	Antony	Julius	The	Hamlet	Othello	Macbeth	•••
	and	Caesar	Tempest				
	Cleopatra						
Antony	1	1	0	0	0	1	
Brutus	1	1	0	1	0	0	
Caesar	1	1	0	1	1	1	
Calpurnia	0	1	0	0	0	0	
Cleopatra	1	0	0	0	0	0	
mercy	1	0	1	1	1	1	
worser	1	0	1	1	1	0	

To answer the query Brutus AND Caesar AND NOT Calpurnia, we take the vectors for Brutus, Caesar and Calpurnia, complement the last, and then do a bitwise AND:

110100 AND 110111 AND 101111 = 100100

Information Retrieval 101:

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Cleopatra	1	0	0	0	0	0	
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worser	1	0	1	1	1	0	

Obviously, this approach can only scale so far...

(as it happens, "so far" is actually not very far in this case)

One solution: build an index mapping terms to the documents in which they may be found.



Example from Manning et al.'s "Introduction to Information Retrieval"



Resolving a query now becomes a set operation on the posting lists...

... i.e., resolving the query "Brutus AND Calpurnia" would simply require intersecting their respective posting lists.

Note the order of the postings!



Postings generally include some sort of "payload" or "metadata:"

- Term frequency
- Term positions within the document
- Context surrounding the term
- PoS information
- etc.

DocIDs can be assigned randomly, or according to some scheme (documents from same domain get similar IDs, higher PageRank gets lower IDs, etc.)

Indexing considerations:

A "web scale" corpus will involve billions of pages...

... and remember: some pages (news sites, etc.) become "stale" quickly, and must be reindexed often.

Bottleneck with inverted indexing: having to visit each document.

Can we speed it up by distributing the work?

Of course we can!



This is what MapReduce was invented for...

Of course we can!

- 2: **procedure** MAP(docid n, doc d)
- 3: $H \leftarrow \text{new AssociativeArray}$
- 4: **for all** term $t \in \text{doc } d$ **do**
- 5: $H\{t\} \leftarrow H\{t\} + 1$
- 6: **for all** term $t \in H$ **do**
- 7: EMIT(term *t*, posting $\langle n, H\{t\}\rangle$)
- 1: class Reducer
- 2: **procedure** REDUCE(term *t*, postings $[\langle n_1, f_1 \rangle, \langle n_2, f_2 \rangle \dots])$
- 3: $P \leftarrow \text{new List}$
- 4: **for all** posting $\langle a, f \rangle \in \text{postings} [\langle n_1, f_1 \rangle, \langle n_2, f_2 \rangle \dots]$ **do** 5: $P.\text{Add}(\langle a, f \rangle)$
- 6: *P*.Sort()
- 7: EMIT(term t, postings P)



1: class MAPPER

- 2: **procedure** MAP(docid n, doc d)
- 3: $H \leftarrow \text{new AssociativeArray}$
- 4: **for all** term $t \in \text{doc } d$ **do**
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6:

7:

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 - $P \leftarrow \text{new List}$
- 4: **for all** posting $\langle a, f \rangle \in \text{postings} [\langle n_1, f_1 \rangle, \langle n_2, f_2 \rangle \dots]$ **do** 5: *P*.Add($\langle a, f \rangle$)
 - $\begin{array}{c} P.SORT() \\ EMIT(term t, postings P) \end{array}$

1: **class** MAPPER

2:	method MAP(docid n , doc d)
3:	$H \leftarrow \text{new AssociativeArray}$
4:	for all term $t \in \text{doc } d$ do
5:	$H\{t\} \leftarrow H\{t\} + 1$
6:	for all term $t \in H$ do
7:	EMIT(tuple $\langle t, n \rangle$, tf $H\{t\}$)
1:	class Reducer
2:	method Initialize
3:	$t_{prev} \leftarrow \emptyset$
4:	$P \leftarrow \text{new PostingsList}$
5:	method REDUCE(tuple $\langle t, n \rangle$, tf [<i>f</i>])
6:	if $t \neq t_{prev} \wedge t_{prev} \neq \emptyset$ then
7:	EMIT(term t , postings P)
8:	P.Reset()
9:	$P.Add(\langle n, f \rangle)$
10:	$t_{prev} \leftarrow t$
11:	method CLOSE
12:	EMIT(term t , postings P)

Being clever with our keys lets the runtime do more of the work.

Remember, keys arrive at the reducer in sorted order, guaranteed. For very large corpora, it's important to be clever about how we store our postings lists on disk...

Out of scope for today, but worth reading Lin & Dyer's summary.

There are two main strategies for breaking up an index onto multiple machines:

1.Document sharding

2.Term sharding



In document sharding, each machine has a portion of the documents, and queries are processed by each machine.

There are two main strategies for breaking up an index onto multiple machines:

1.Document sharding

2.Term sharding



In term sharding, each machine has a the full posting list for a subset of the terms, and only sees the part of the query that is relevant to it.

There are tradeoffs to each:

Document sharding is simpler to process, but requires a lot of wasted work...

- Each shard can process independent queries
- Easy to keep around more per-document information
- Each query must involve every shard (O(*k**N) disk accesses, for *k* query terms and *N* document shards)

There are tradeoffs to each:

Term sharding is arguably more efficient to process, but requires a lot more complexity.

- *Far* less time spent doing I/O to access index (only *k* shards are involved for a *k*-word query)...

- Harder to have per-doc word-level information

- Much more network bandwidth needed (data from each matching doc must be aggregated)

- There's no single right answer for all cases, but in general, document sharding seems better...
- ... largely due to lower search latency, which is the most relevant metric.

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Quick MT overview

Map-Reduce & MT Model Estimation

$$P(f_{1}^{m}|e_{1}^{l}) = \sum_{a_{1}^{m}} P(f_{1}^{m}, a_{1}^{m}|e_{1}^{l})$$

$$\int \sum_{a_{1}^{m}} P(a_{1}^{m}|e_{1}^{l}, f_{1}^{m}) \prod_{j=1}^{m} P(f_{j}|e_{a_{j}})$$
Foreign Sentence

$$P(f_{1}^{m}|e_{1}^{l}) = \sum_{a_{1}^{m}} P(f_{1}^{m}, a_{1}^{m}|e_{1}^{l})$$

$$= \sum_{a_{1}^{m}} P(a_{1}^{m}|e_{1}^{l}, f_{1}^{m}) \prod_{j=1}^{m} P(f_{j}|e_{a_{j}})$$
Original Sentence

$$P(f_{1}^{m}|e_{1}^{l}) = \sum_{a_{1}^{m}} P(f_{1}^{m}, a_{1}^{m}|e_{1}^{l})$$
$$= \sum_{a_{1}^{m}} P(a_{1}^{m}|e_{1}^{l}, f_{1}^{m}) \prod_{j=1}^{m} P(f_{j}|e_{a_{j}})$$
$$(1)$$
Language model

$$P(f_{1}^{m}|e_{1}^{l}) = \sum_{a_{1}^{m}} P(f_{1}^{m}, a_{1}^{m}|e_{1}^{l})$$

$$= \sum_{a_{1}^{m}} P(a_{1}^{m}|e_{1}^{l}, f_{1}^{m}) \prod_{j=1}^{m} P(f_{j}|e_{a_{j}})$$

$$\int_{1}^{1} \text{Translation model}$$

$$\hat{a}_{1}^{m} = \arg\max_{a_{1}^{m}} P(a_{1}^{m}|e_{1}^{l}, f_{1}^{m}) \prod_{j=1}^{m} P(f_{j}|e_{a_{j}})$$

Fast, Easy, and Cheap: Construction of Statistical Machine Translation Models with MapReduce, Christopher Dyer et. al., Proc. ACL Workshop on Statistical Machine Translation, pg. 199-207, 2008. slides

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$$P(f_1^m | e_1^l) = \sum_{a_1^m} P(f_1^m, a_1^m | e_1^l)$$
$$= \sum_{a_1^m} P(a_1^m | e_1^l, f_1^m) \prod_{j=1}^m P(f_j | e_{a_j})$$

1-best translation guess

$$\hat{a}_{1}^{m} = \arg\max_{a_{1}^{m}} P(a_{1}^{m}|e_{1}^{l}, f_{1}^{m}) \prod_{j=1}^{m} P(f_{j}|e_{a_{j}})$$

More data == better LM (and MT)



More data == better LM (and MT)



How to estimate the LM?

$$P(w_1^L) = \prod_{i=1}^L P(w_i | w_1^{i-1}) \approx \prod_{i=1}^L \hat{P}(w_i | w_{i-n+1}^{i-1})$$

$$P_{MLE}(B|A) = \frac{c(A,B)}{c(A)} = \frac{c(A,B)}{\sum_{B'} c(A,B')}$$

When corpora get big...

Fast, Easy, and Cheap: Construction of Statistical Machine Translation Models with MapReduce, Christopher Dyer et. al., Proc. ACL Workshop on Statistical Machine Translation, pg. 199-207, 2008. slides

Large Language Models in Machine Translation. Thorsten Brants et. al., Proc. Joint Conference on Empirical Methods in Natural Language Processing and Computational Natural Language Learning (EMNLP), pg. 858-867, 2007.

MLE estimation in Map-Reduce:

Method 1

Map ₁	$\langle A, B \rangle \to \langle \langle A, B \rangle, 1 \rangle$
Reduce ₁	$\langle \langle A, B \rangle, c(A, B) \rangle$
Map_2	$\langle \langle A, B \rangle, c(A, B) \rangle \to \langle \langle A,^* \rangle, c(A, B) \rangle$
Reduce ₂	$\langle \langle A,^* \rangle, c(A) \rangle$
Map ₃	$\langle \langle A, B \rangle, c(A, B) \rangle \to \langle A, \langle B, c(A, B) \rangle \rangle$
Reduce ₃	$\langle A, \langle B, \frac{c(A,B)}{c(A)} \rangle \rangle$

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Method 2

Map ₁	$\langle A, B \rangle \to \langle \langle A, B \rangle, 1 \rangle; \langle \langle A,^* \rangle, 1 \rangle$
Reduce ₁	$\langle \langle A, B \rangle, \frac{c(A,B)}{c(A)} \rangle$

on in Map-Reduce:

Method 1

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map

Map ₁	$\langle A, B \rangle \to \langle \langle A, B \rangle, 1 \rangle$
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Method 2

Map ₁	$\langle A, B \rangle \to \langle \langle A, B \rangle, 1 \rangle; \langle \langle A, * \rangle, 1 \rangle$
Reduce ₁	$\langle \langle A, B \rangle, \frac{c(A,B)}{c(A)} \rangle$

Method 3

Map ₁	$\langle A, B_i \rangle \to \langle A, \langle B_i : 1 \rangle \rangle$
Reduce ₁	$\langle A, \langle B_1 : \frac{c(A,B_1)}{c(A)} \rangle, \langle B_2 : \frac{c(A,B_2)}{c(A)} \rangle \cdots \rangle$



We can use a similar method for estimating parameters for alignments:







 $P(a_1^m | e_1^l, f_1^m)$



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